

Walamitien Hervé Oyenán

<http://people.cis.ksu.edu/~oyenan>

INTERESTS

RESEARCH INTERESTS

Areas: Software Engineering, Intelligent Systems, Cooperative Robotics, Wireless Sensor Networks.

My current research centers primarily in the areas of **Software Engineering and Multiagent Systems**. My general objective is to develop **adaptive intelligent systems** that can perform optimally with minimum human intervention. In particular, I am focusing on creating models and techniques for the systematic design and development of adaptive and autonomous multiagent systems in domains such as **Cooperative Robotics** and **Wireless Sensor Networks**.

TEACHING INTERESTS

Areas: Software Engineering, Artificial Intelligence, Multiagent Systems, Distributed Systems.

EDUCATION

- **Ph.D. in Computer Science,** May 2010
Kansas State University, Manhattan, Kansas
Thesis Title: "An Algebraic Framework for Compositional Design of Autonomous, Adaptive Multiagent Systems"
Advisor: Scott DeLoach
- **Master of Software Engineering,** December 2003
Kansas State University, Manhattan, Kansas *GPA: 4.0 / 4.0*
- **B.S. in Computer Science,** June 2001
University of Lille, France *GPA: 3.7 / 4.0*

PROFESSIONAL EXPERIENCE

RESEARCH EXPERIENCE

- **Sr. Research Engineer,** Motorola Solutions August 2010 – present
Applied Research Center
 - Investigate the use of Web 2.0 technologies such as HTML5, JavaScript, and CSS3 for rapid development of robust mobile enterprise applications.
 - Research on software architectures and programming models for a mobile enterprise applications platform.
- **Research Assistant,** Kansas State University January 2005 – May 2010
Multiagent and Cooperative Robotics Lab (Dr. Scott DeLoach)

- Conducted research in applying Software Engineering principles for the compositional design of autonomous and adaptive Multiagent Systems.
- Designed an Adaptive Information System for autonomously gathering tactical information from sensors on a simulated battlefield.
- **Research Assistant,** Kansas State University January 2006 – May 2009
Pervasive Sensor Networks Lab (Dr. Gurdip Singh)
 - Conducted research for providing an agent-based multi-layer approach for designing adaptive Wireless Sensor Networks applications.
 - Implemented prototypes for various detection-based applications (vehicle, intrusion and radiation detection) using heterogeneous wireless sensors in an ad-hoc network.
- **Research Assistant,** Kansas State University May 2003 – January 2004
Parallel and Distributed Computation (Dr. Virgil Wallentine)
 - Implemented a load-balancing algorithm to efficiently distribute the parallel calculation of pipeline computer models among several machines.
 - Designed and developed a GUI for a Pipeline Simulation Software to create pipeline components and visualize their data during simulation.
- **Research Assistant,** Kansas State University January 2003 – May 2003
Operating Systems (Dr. Masaaki Mizuno)
 - Evaluated and redesigned a Java operating system (LeJos) on Lego Mindstorms robots.
 - Studied the impacts of concurrent threads in a multi-thread architecture.
 - Designed an implementation pattern for time-triggered embedded systems.

TEACHING EXPERIENCE

- **Principles of College Teaching** (course taken), Kansas State University Fall 2009
 - Attended a graduate-level course about teaching and learning at the university level.
 - Course focused on learning theory, educational objectives, methods and techniques, college students, and evaluation in the classroom.
- **Teaching Assistant,** Kansas State University Spring 2007
Implementation of Sensor Network Applications (CIS890)
 - Designed and supervised multiple course projects (for graduate students) which integrated robots and wireless sensor networks.
 - Held tutorial sessions to familiarize students with sensor network programming.

WORK EXPERIENCE

- **ARTC Research Intern** Motorola, Schaumburg, IL June 2009 – August 2009
- **Web Developer** FINRA, Washington, DC July 2004 – January 2005
- **Quality Assurance Tester** Welocalize, Frederick, MD March 2004 – January 2005
- **Web Developer Intern** AllSystem, Paris, France June 2002 – August 2002
- **Java Developer Intern** LIFL, Lille, France January 2001 – June 2001

PUBLICATIONS

REFEREED JOURNALS

- **Towards a Systematic Approach for Designing Autonomic Systems**
Walamitien H. Oyen and Scott A. DeLoach.
Web Intelligence and Agent Systems: An International Journal. Volume 8, no. 1, January 2010.
- **A Capabilities Based Model for Artificial Organizations**
Scott A. DeLoach, *Walamitien H. Oyen* and Eric T. Matson.
Journal of Autonomous Agents and Multiagent Systems. Volume 16, no. 1, February 2008.

REFEREED CONFERENCES AND WORKSHOPS

- **An Organizational Design for Adaptive Sensor Networks**
Walamitien H. Oyen, Scott A. DeLoach and Gurdip Singh.
IEEE/WIC/ACM International Conference on Intelligent Agent Technology (IAT 2010). September 2010. Toronto, Canada.
- **A Service-Oriented Approach for Integrating Multiagent System Designs**
Walamitien H. Oyen, Scott A. DeLoach and Gurdip Singh.
The 8th International Conference on Autonomous Agents and Multiagent Systems (AAMAS 2009). May 2009. Budapest, Hungary.
- **Exploiting Reusable Organizations to Reduce Complexity in Multiagent System Design**
Walamitien H. Oyen, Scott A. DeLoach and Gurdip Singh.
The 9th International Workshop on Agent Oriented Software Engineering (AOSE 2009). May 2009. Budapest, Hungary.
- **Design and Evaluation of a Multiagent Autonomic Information System**
Walamitien H. Oyen and Scott A. DeLoach.
IEEE/WIC/ACM International Conference on Intelligent Agent Technology (IAT 2007). November 2007. Fremont, California.
- **O-MaSE: A Customizable Approach to Developing Multiagent Development Processes**
Juan C. Garcia-Ojeda, Scott A. DeLoach, Robby, *Walamitien H. Oyen* and Jorge Valenzuela.
The 8th International Workshop on Agent Oriented Software Engineering (AOSE 2007). May 2007. Honolulu, Hawaii.

TECHNICAL REPORTS

- **Designing Adaptive Sensor Networks using an Organization-based Approach**
Scott A. DeLoach and *Walamitien H. Oyen*.
Multiagent and Cooperative Robotics Laboratory Technical Report No. MACR-TR-2010-04. Kansas State University. June 2010.

- **An Organizational Model and Dynamic Goal Model for Autonomous, Adaptive Systems**
Scott A. DeLoach and Walamitien H. Oyen.
Multiagent and Cooperative Robotics Laboratory Technical Report No. MACR-TR-2006-01. Kansas State University. March 2006.
- **Graphical User Interface and Job Distribution Optimizer for a Virtual Pipeline Simulation Testbed**
Walamitien H. Oyen.
Master of Software Engineering Report. Kansas State University. December 2003.

SERVICES & PROFESSIONAL AFFILIATIONS

- **Member**, Association for Computing Machinery (ACM)
- **Student Representative**, Dean of Engineering Interview process, March 2007
- **Panelist**, Graduate Student Panel at STEM (Science, Technology, Engineering, and Mathematics) Graduate Fair, November 2006
- **Judge**, High School Programming Contest, October 2006